iArm Turns Vice Handle via Remote Trajectory Interface

Administrator, Monday 25 June 2012 - 05:05:37

A pose is found where the iArm can hold and turn the vice handle. A safe trajectory to this position is recorded on a remote WinXP PC. Then the trajectory is controlled via a control loop running on a remote WinXP PC using ZeroC Ice calls back and forwards to the Linux Laptop connected to the iArm CAN bus.

The vice handle is NOT sensed in this video. This is NOT controlled by a human operator.